

# Programmes en Micropython SmartHome

## Test Led pin 12

[exemple001.py](#)

```
from machine import Pin
import time

led = Pin(12, Pin.OUT)# Build an LED object, connect the external LED
light to pin 0, and set pin 0 to output mode
while True:
    led.value(1)# turn on led
    time.sleep(1)# delay 1s
    led.value(0)# turn off led
    time.sleep(1)# delay 1s
```

## Test Led PWM

[exemple002.py](#)

```
import time
from machine import Pin,PWM

#The way that the ESP32 PWM pins output is different from traditionally
controllers.
#It can change frequency and duty cycle by configuring PWM's parameters
at the initialization stage.
#Define GPIO 0's output frequency as 10000Hz and its duty cycle as 0,
and assign them to PWM.
p0 = Pin(012, Pin.OUT)
pwm = PWM(p0, freq=10000, duty_u16=8192)

try:
    while True:
#The range of duty cycle is 0-1023, so we use the first for loop to
control PWM to change the duty
#cycle value,making PWM output 0% -100%; Use the second for loop to
make PWM output 100%-0%.
        for i in range(0,1023):
            pwm.duty(i)
            time.sleep_ms(1)

        for i in range(0,1023):
```

```
        pwm.duty(1023-i)
        time.sleep_ms(1)
except:
    #Each time PWM is used, the hardware Timer will be turned ON to
    #cooperate it. Therefore, after each use of PWM,
    #deinit() needs to be called to turned OFF the timer. Otherwise, the
    #PWM may fail to work next time.
    pwm.deinit()
```

## Test des 2 Boutons

[exemple003.py](#)

```
from machine import Pin
import time

button1 = Pin(16, Pin.IN, Pin.PULL_UP)
button2 = Pin(27, Pin.IN, Pin.PULL_UP)

while True:
    btnVal1 = button1.value() # Reads the value of button 1
    btnVal2 = button2.value()
    print("button1 =", btnVal1) #Print it out in the shell
    print("button2 =", btnVal2)
    time.sleep(0.1) #delay 0.1s
```

## Test Bouton 1 M/A Led

[exempl004.py](#)

```
from machine import Pin
import time

button1 = Pin(16, Pin.IN, Pin.PULL_UP)
led = Pin(12, Pin.OUT)
count = 0

while True:
    btnVal1 = button1.value() # Reads the value of button 1
    #print("button1 =", btnVal1) #Print it out in the shell
    if(btnVal1 == 0):
        time.sleep(0.01)
        while(btnVal1 == 0):
            btnVal1 = button1.value()
```

```
        if(btnVal1 == 1):
            count = count + 1
            print(count)
    val = count % 2
    if(val == 1):
        led.value(1)
    else:
        led.value(0)
    time.sleep(0.1) #delay 0.1s
```

## Test PIR : detection de personnes

[exemple005.py](#)

```
from machine import Pin
import time

PIR = Pin(14, Pin.IN)
while True:
    value = PIR.value()
    print(value, end = " ")
    if value == 1:
        print("Des personnes sont dans la zone ...!")
    else:
        print("il n'y a personne ...!")
    time.sleep(0.1)
```

## Test Buzzer Music

[exemple006.py](#)

```
from machine import Pin, PWM
from time import sleep
buzzer = PWM(Pin(25))

buzzer.duty(1000)

# Happy birthday
buzzer.freq(294)
sleep(0.25)
buzzer.freq(440)
sleep(0.25)
buzzer.freq(392)
sleep(0.25)
buzzer.freq(532)
```

```
sleep(0.25)
buzzer.freq(494)
sleep(0.25)
buzzer.freq(392)
sleep(0.25)
buzzer.freq(440)
sleep(0.25)
buzzer.freq(392)
sleep(0.25)
buzzer.freq(587)
sleep(0.25)
buzzer.freq(532)
sleep(0.25)
buzzer.freq(392)
sleep(0.25)
buzzer.freq(784)
sleep(0.25)
buzzer.freq(659)
sleep(0.25)
buzzer.freq(532)
sleep(0.25)
buzzer.freq(494)
sleep(0.25)
buzzer.freq(440)
sleep(0.25)
buzzer.freq(698)
sleep(0.25)
buzzer.freq(659)
sleep(0.25)
buzzer.freq(532)
sleep(0.25)
buzzer.freq(587)
sleep(0.25)
buzzer.freq(532)
sleep(0.5)
buzzer.duty(0)
```

## Test Servo Porte entrée : angle 25° 77° 180°

[exemple007.py](#)

```
from machine import Pin, PWM
import time
pwm = PWM(Pin(13))
pwm.freq(50)

...

```

```
Duty cycle corresponding to the Angle
```

```
0°----2.5%----25  
45°----5%----51.2  
90°----7.5%----77  
135°----10%----102.4  
180°----12.5%----128  
...
```

```
angle_0 = 25  
angle_90 = 77  
angle_180 = 128
```

```
while True:  
    pwm.duty(angle_0)  
    time.sleep(1)  
    pwm.duty(angle_90)  
    time.sleep(1)  
    pwm.duty(angle_180)  
    time.sleep(1)
```

## Test Capteur Humidité 0= Fenetre Ouverte, 0> Fenetre fermée

[exemple008.py](#)

```
# Import Pin, ADC and DAC modules.  
from machine import ADC, Pin, DAC, PWM  
import time  
pwm = PWM(Pin(5))  
pwm.freq(50)  
  
# Turn on and configure the ADC with the range of 0-3.3V  
adc=ADC(Pin(34))  
adc.atten(ADC.ATTN_11DB)  
adc.width(ADC.WIDTH_12BIT)  
  
# Read ADC value once every 0.1seconds, convert ADC value to DAC value  
# and output it,  
# and print these data to "Shell".  
try:  
    while True:  
        adcVal=adc.read()  
        dacVal=adcVal//16  
        voltage = adcVal / 4095.0 * 3.3  
        print("ADC  
Val:", adcVal, "DACVal:", dacVal, "Voltage:", voltage, "V")  
        if(voltage > 0.6):  
            pwm.duty(46)  
        else:  
            pwm.duty(100)
```

```
        time.sleep(0.1)
except:
    pass
```

## Test Neopixels : Blanc, Rouge, Vert, Bleu

[exemple009.py](#)

```
#Import Pin, neopiexl and time modules.
from machine import Pin
import neopixel
import time

#Define the number of pin and LEDs connected to neopixel.
pin = Pin(26, Pin.OUT)
np = neopixel.NeoPixel(pin, 4)

#brightness :0-255
brightness=100
colors=[[brightness,0,0],           #red
        [0,brightness,0],          #green
        [0,0,brightness],          #blue
        [brightness,brightness,brightness], #white
        [0,0,0]]                   #close

#Nest two for loops to make the module repeatedly display five states
of red, green, blue, white and OFF.
while True:
    for i in range(0,5):
        for j in range(0,4):
            np[j]=colors[i]
            np.write()
            time.sleep_ms(50)
        time.sleep_ms(500)
    time.sleep_ms(500)
```

## Test Bouton et Neopixels Bp2 + incremente les couleurs Bp1 - decrementre les couleurs

[exemple010.py](#)

```
#Import Pin, neopiexl and time modules.
from machine import Pin
import neopixel
```

```
import time

button1 = Pin(16, Pin.IN, Pin.PULL_UP)
button2 = Pin(27, Pin.IN, Pin.PULL_UP)
count = 0

#Define the number of pin and LEDs connected to neopixel.
pin = Pin(26, Pin.OUT)
np = neopixel.NeoPixel(pin, 4)

#brightness :0-255
brightness=100
colors=[[0,0,0],
        [brightness,0,0],           #red
        [0,brightness,0],         #green
        [0,0,brightness],        #blue
        [brightness,brightness,brightness] #white
        ]                          #close

def func_color(val):
    for j in range(0,4):
        np[j]=colors[val]
        np.write()
        time.sleep_ms(50)

#Nest two for loops to make the module repeatedly display five states
of red, green, blue, white and OFF.
while True:
    btnVal1 = button1.value() # Reads the value of button 1
    #print("button1 =",btnVal1) #Print it out in the shell
    if(btnVal1 == 0):
        time.sleep(0.01)
        while(btnVal1 == 0):
            btnVal1 = button1.value()
            if(btnVal1 == 1):
                count = count - 1
                print(count)
                if(count <= 0):
                    count = 0

    btnVal2 = button2.value()
    if(btnVal2 == 0):
        time.sleep(0.01)
        while(btnVal2 == 0):
            btnVal2 = button2.value()
            if(btnVal2 == 1):
                count = count + 1
                print(count)
                if(count >= 4):
                    count = 4
```

```
if(count == 0):  
    func_color(0)  
elif(count == 1):  
    func_color(1)  
elif(count == 2):  
    func_color(2)  
elif(count == 3):  
    func_color(3)  
elif(count == 4):  
    func_color(4)
```

## Test ventilateur dans les 2 sens

[exemple011.py](#)

```
from machine import Pin,PWM  
import time  
#Two pins of the motor  
p0 = Pin(19,Pin.OUT)  
p1 = Pin(18,Pin.OUT)  
#INA =PWM(po,10000,0)#INA corresponds to IN+  
#INB =PWM(p1,10000,2)#INB corresponds to IN-  
INA = PWM(p0, freq=10000, duty_u16=8192)  
INB = PWM(p1, freq=10000, duty_u16=8192)  
  
try:  
    while True:  
        #Counterclockwise 4s  
        INA.duty(0) #The range of duty cycle is 0-1023  
        INB.duty(700)  
        time.sleep(4)  
        #stop 2s  
        INA.duty(0)  
        INB.duty(0)  
        time.sleep(2)  
        #Turn clockwise for 4s  
        INA.duty(600)  
        INB.duty(0)  
        time.sleep(4)  
        #stop 2s  
        INA.duty(0)  
        INB.duty(0)  
        time.sleep(2)  
except:  
    INA.duty(0)  
    INB.duty(0)
```

```
INA.deinit()
INB.deinit()
```

## Bouton1 commande ventilateur

[exemple012.py](#)

```
from machine import Pin,PWM
import time
#Two pins of the motor
p0 = Pin(19,Pin.OUT)
p1 = Pin(18,Pin.OUT)
INA =PWM(p0,freq=10000, duty_u16=8192)#INA corresponds to IN+
INB =PWM(p1,freq=10000, duty_u16=8192)#INB corresponds to IN-

button1 = Pin(16, Pin.IN, Pin.PULL_UP)
#button2 = Pin(27, Pin.IN, Pin.PULL_UP)
count1 = 0
#count2 = 0

try:
    while True:
        btnVal1 = button1.value() # Reads the value of bouton 1
        # btnVal2 = button2.value() # lecture bouton 2
        #####
        if(btnVal1 == 0):
            time.sleep(0.01)
            while(btnVal1 == 0):
                btnVal1 = button1.value()
                if(btnVal1 == 1):
                    count1 = count1 + 1
                    print("compl" , count1)
        val1 = count1 % 2
        if(val1 == 1):
            INA.duty(0) #The range of duty cycle is 0-1023
            INB.duty(700)
        else:
            INA.duty(0)
            INB.duty(0)
except:
    INA.duty(0)
    INB.duty(0)
    INA.deinit()
    INB.deinit()
```

From: <https://magenealogie.chanterie37.fr/www/fablab37110/> - **Castel'Lab le Fablab MJC de Château-Renault**

Permanent link: <https://magenealogie.chanterie37.fr/www/fablab37110/doku.php?id=start:arduino:esp32:smart:micropython&rev=1740581680>

Last update: **2025/02/26 15:54**

